## STRUCTURE-ADAPTIVE PARALLEL SOLUTION OF SPARSE TRIANGULAR LINEAR SYSTEMS <br> EHSAN TOTONI

## Sparse Triangular Solution

$\square$ Used in solution of linear systems, least squares

- Many times iteratively
$\square$ Direct methods (after factorization)
- many right-hand sides
- Refinement of solution
$\square$ Iterative methods
- kernel in Gauss-Seidel method
- Preconditioners
- E.g. Incomplete-Cholesky before Conjugate Gradient


## Poor Parallelism

$$
x_{i}=\left(b_{i}-\sum_{j=1}^{i-1} l_{i j} x_{j}\right) / l_{i i}, \quad i=1, \ldots, n
$$

$\square$ Minimal concurrency

- Lots of structural dependencies
$\square$ Small work per data
- Just one multiply-add for most entries!
$\square$ Sparse: Some parallelism


## Poor Parallelism

$\square$ Slower than sequential!

- HYPRE and SuperLU_DIST
$\square$ Some progress in shared-memory
$\square$ Has to be done in parallel
- Matrix is already distributed
- E.g. by factorization
- Memory is constrained
$\square$ Bottle-neck of many methods


## Basics Approach



## Basic Approach-Reordering



## Dense Regions



## Algorithm- high level view



## Implementation in Charm++

$\square$ Chare array for blocks of columns

- Virtualization
- Built-in round-roubin
- Priority of data messages over compute
$\square$ Message aggregation
$\square$ Virtualization ratio trade-off
$\square$ More effort but possible
$\square$ Multiple column blocks per processor
- Virtualization illusion
- Mapping
$\square$ MPI_lprobe for priorities
$\square$ Give up virtualization
- For easy programming
- Some performance loss


## Evaluation

$\square$ Performance highly depends on matrix structure!
$\square$ Real application matrices

- Many different ones
- Strong scaling (pretty small matrices!)
$\square$ Up to 512 nodes of BG/P
- 1 core per node
$\square$ Simple sequential kernel
$\square$ Comparison with standard packages
- HYPRE, SuperLU_DIST


## Benchmark matrices

| Name | Dimension | Independent <br> rows | Nonzeros | Nondiagonal <br> Nonzero | Domain |
| :--- | :--- | :--- | :--- | :--- | :--- |
| circuit5M dc | $3,523,317$ | 674,311 | $10,631,719$ | $4,110,848$ | circuit <br> simulation |
| slu c-big | 345,241 | 345,141 | 499,807 | 17,038 | optimization |
| slu bbmat | 38,744 | 6,735 | $17,819,183$ | $15,762,657$ | fluid <br> dynamics |
| nlpkkt1 20 | $3,542,400$ | $1,814,400$ | $50,194,096$ | $46,651,696$ | optimization |
|  |  |  | $\ldots$ |  |  |

## Matrix structures


(a) nlpkkt120

(b) Geo_1438

(c) slu_c-big

(d) Freescale 1

(e) circuit5M

## No-fill Incomplete-LU scaling



## Complete-LU scaling



## Comparison to HYPRE



## Comparison to SuperLU_DIST



## Analysis time



## Conclusion

> Parallel solution of sparse triangular systems
> Needed for many solvers
$>$ Notoriously hard to parallelize!
> A novel parallel algorithm
> Many heuristics
$>$ Analysis and reordering
> Implementation in Charm++
> Useful features such as virtualization

## Future work

$\square$ Mapping column blocks to processors

- Better balance
- Less communication latency
$\square$ Smart priorities
- Different blocks
- data messages
$\square$ Virtualization ratio
$\square$ Message aggregation


## Questions?



