Threads for Interoperable Parallel Programming

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**Converse Goals**

- To facilitate building of runtime systems for parallel languages.
- To achieve portability across many platforms.
- **Multilingual Interoperability:**
  - the ability to link modules written in different parallel languages.
Converse Threads: Features

1. User control over thread scheduling.
2. User control over preemption and nonpreemption.
3. Low-cost primitive abstractions.
4. Useful model for shared and private data.
Feature 1: User control over thread scheduling

A good thread-scheduler should support all kinds of thread execution orders. Such orders might include:

- Critical-path intensive.
- Depth-First.
- Resource-bound.
User control over thread scheduling

User control over scheduling can be achieved using a hierarchical scheduling model.
Feature 2: User control over Preemption

- Problems with Preemptive Context Switching:
  - Must write all subroutines to be reentrant.
  - High cost due to frequent locking.

- Problems with Manual Context-Switching:
  - Increased possibility of I/O latency.
  - Priorities not kept as current as with preemption.
  - Preemption is part of many Parallel Programming models.

- Converse Solution:
  - allow each thread to choose whether it is preemptible.
Feature 3: Low-Cost Abstraction Layer

- Parallel programs may create thousands of threads.
- Threads have to be inexpensive.
- Synchronization abstractions have to be inexpensive.
- Thread-Private data must be inexpensive.
Low-Cost Abstraction Layer: Primitives

- Explicit context-switching.
- Explicit thread-handles and thread-queues.
- Macro interface to thread-private data.
- Multiple levels of sharing/synchronization.
Feature 4: a Usable Model for Shared Data.

Three possible levels of data-sharing are recognized:

- Thread-Private Data (completely unshared).
- Processor-Private Data (shared by all threads on 1 CPU).
- Semi-Shared Data (shared within one physical address space).

Simulated “global variables” are provided with each level of sharing.
Processor-Private Variable Declaration and Use

CpvDeclare(int, x);

incx() { CpvAccess(x) = CpvAccess(x) + 1; }

main() { CpvInitialize(int, x); ... }
Converse Threads API: Creation/Destruction

- typedef struct CthThreadStruct *CthThread;
  - the thread datatype, an opaque type.

- CthThread CthCreate(void (*fn)(void *), void *arg, int size)
  - create a thread, return its handle.

- CthThread CthSelf()
  - return the thread which is currently executing.

- void CthFree(CthThread t)
  - free the specified thread
Converse Threads API: Context-Switching

- void CthResume(CthThread t)
  - immediately context switch to thread t

- void CthSuspend();
  - transfer to any thread in the appropriate ready-queue.

- void CthAwaken(CthThread t);
  - add thread t to the appropriate ready-queue.

- void CthYield();
  - put self on ready-queue, then yield to another thread
Converse Threads API: High-Level Control

- void CthSigYieldEnable(int flag);
  - enable/disable preemption of the current thread.
- void CthAutoYield(int usec);
  - enable time-sliced preemption of current thread.
- void CthSetStrategy(CthThread t, ...)
  - choose ready-queue and scheduler to use for thread t.
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