

# **Mapping Applications on Irregular Allocations**

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### Abstract

- Mapping applications on clusters becomes more difficult as the number of nodes become larger
- Supercomputers assigns allocations with irregular shapes to users to maximize the utilization of resources
- Much more difficult to map applications on these irregular allocations
- We extended Rubik, a python based framework to map applications on irregular allocations with a few lines of python codes
- o Rubik was originally designed for regular allocations, so we added features to handle allocations with irregular structure and unavailable nodes and two mapping algorithms such as row-ordering and recursive splitting
- We evaluate our work with two widely used HPC applications on Blue Waters: MILC and Qbox
- We reduce execution time by 32.5% in MILC and by 36.3% in Qbox, and communication time by 60% in MILC and 56% in Qbox

## Rubik, a python framework for structured communication



#	Create app partition tree of 64-task planes
	app = box([8,8])
	app.tile([8,1])
#	Create network partition tree of 64-processor cube
	network = box([4, 4, 4])
	network.tile([2,2,2])
	network man(app) \# Map Task planes into cubes

- Rubik is a python based framework developed at LLNL for mapping applications with structured communication onto regular allocation[1]
- Rubik facilitates mapping of user application using a few lines of python code
- Users can easily general several different mappings for their applications
- Rubik supports many types of operations for better mapping of application grids onto network grids

### Limitation of Rubik for irregular allocations

· Rubik is designed for mapping applications onto regular and symmetrical allocations

- · However, in many cases, the shapes of the allocations are irregular as the Blue Waters
- (Gray -> compute nodes, red -> XK nodes, blue-> service nodes)
- · Motivation of this work: how to enable use of Rubik on irregular allocations for its broader applicability



[1] A. Bhatele et al., "Mapping applications with collectives over sub-communicators on torus networks," High Performance Computing, Networking, Storage and sis (SC). 2012 Inte al Conference for, Salt Lake City, UT, 2012, pp. 1-11. doi: 10.1109/SC.2012.75



# **Projecting Algorithm**



# **Optimizations**

- The direction of splitting
  - Calculate bisection bandwidth in each splitting and choose the direction where the bisection BW is lowest
    - bandwidth between closest subcuboids
- The shape of the virtual network grid
- Estimate the shape of the virtual network grid with the shape of the allocation
- Factorize the number of tasks and use factors by this factorization for the estimation E.g.) 9 x 2 x 8 allocation, 4096 ranks
  - Factorize 4096 -> 2<sup>12</sup>
  - Start from 1 x 1 x 1 -> multiply each dimension with factors until each dimension become equal or larger than the corresponding dimension of the allocation
  - 1 x 1 x 1 -> 2 x 1 x 1 -> 2 x 2 x 2 -> 4 x 2 x 2 -> 4 x 2 x 4 (herause v dimension is already 2) -> 8 x 2 x 4 -> 8 x 2 x 8 (done)

# **Experimental Results**

#### Configuration for experiments



- 59.3% improved in communication
- With many number of cores. MILC spent more time on communication

are more improved than collective operations Optimization to estimate the shape of the virtual network

grid seems effective in more irregular allocations with more number of cores The random shape of the virtual network grid can increase

hops between ranks by inefficient placement of ranks

SCALAPACK in each graph include elapsed time

In 16384 ranks, most of reduction comes from

MPI routines significantly

the reduction in SCALAPACK

for functions in SCLAPACK and most of them use



#### Ohox

- 36.3% improved in execution
- 59.3% improved in communication
- Qbox doesn't call p2p routines directly. Instead, it uses SCALAPACK for p2p communication between ranks

alized Total Execution Time, 16384 Rank



- Input: the shape of the allocation, number of tasks Output:  $\mathcal{V}$ : Direction vector for the Recursive Splitting 1: partition  $\leftarrow$  the shape of the allocation 2: factors  $\leftarrow$  factorise (the number of tasks) 3: factorIdx  $\leftarrow 0$  $\begin{array}{l} \mbox{factorIds} \leftarrow 0 \\ B \leftarrow calculate bandwidth between subcuboids by factors[factorIdx] in each axis \\ \mbox{while product(partition)} > 1 \mbox{ do } \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in C and the current bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis where the bandwidth in B is lowest \\ \mbox{currentAxis} \leftarrow choose axis wh$  $\begin{array}{l} \mbox{partition[currentAxis]} \leftarrow \mbox{partition[currentAxis] / factors[factorldx]} \\ \mbox{B[currentAxis]} \leftarrow \mbox{B[currentAxis] / factors[factorldx]} \\ \mbox{Add currentAxis to } \mathcal{V} \end{array}$  $torIdx \leftarrow factorIdx + 1$
- 11: end while

To maximize the bisection